Anesthesia Patient Safety Foundation

These slides were posted to the MD PnP website: https://mdpnp.mgh.harvard.edu/md-pnp-apsf-stelting-workshop/

APSF Stoelting Conference 2023

"Emerging Medical Technologies – A Patient Safety Perspective on Wearables, Big Data and Remote Care" https://www.apsf.org/event/apsf-stoelting-conference-2023/

Las Vegas, NV Sept 6-7, 2023

# Session 4: Impending Issues: Disruptors and Innovation Remote control of Medical Devices – Are we ready?



Julian M. Goldman, MD Anesthesiologist, Massachusetts General Hospital Medical Director, Biomedical Engineering, Mass General Brigham Director, MGH Medical Device Interoperability & Cybersecurity Program

Boston, MA, USA





# Recent applicable US Gov Research Support

No financial conflicts to disclose

- DOD/TiDE Remote Control of Mechanical Ventilators W81XWH-15-9-001
- DoD/Device Interoperability and Autonomy Coordinating Center (DIACC) – 1160555
- DoD/An Interoperable Platform for Real-Time In-Theater Caregiver Decision Support (RTCDS) - W81XWH-17-C-0251
- DoD/Semiautonomous Anesthesia and Sedation Devices for Military Medical Care - W81XWH-22-9-0004
- DoD/TiDE Accelerating Medical Device Interoperability and Autonomy (MDIA)



# About the MGH MD PnP Program

Medical Device "Plug-and-Play" Interoperability & Cybersecurity Program

Founded in 2004 to improve patient care by enabling innovation of advanced safe, secure, and interoperable medical devices and digital health technologies (http://mdpnp.mgh.harvard.edu/)

- Impetus: Absence of interoperability impeded innovation in MGH OR of the Future (2002)
- Convened development of ICE standard Integrated Clinical Environment (\* 2009) ICE = Platform + Devices + Apps
- Developed OpenICE open-source interoperability research platform (www.openice.info) (NIH U01)
- Collaborative lab prototyping and public demonstrations with industry, academia, and government ٠
- Collaboration Agreements with FDA/CDRH, VA, and DoD/TATRC ٠
- Industry service portfolios / lab testing





<sup>\*</sup>ICE Standard was originally published as ASTM F2761-09, then AAMI 2700-1

RESEARCH COLLABORATION AGREEMENT Between U.S. Food and Drug Administration and the Massachusetts General Hospital

> FDA PI: Sandy Weininger, Ph.D. Office/Center: FDA/CDRH/OSEL/DBP

Collaborator PI: Julian M. Goldman, M.D. Collaborator: Massachusetts General Hospital

> Effective Date: January 11, 2016 Expiration: January 11, 2027

#### Goals:

CDRH and MGH will collaborate to improve the safety, security, and effectiveness of medical devices used in interoperable systems, including promoting the use of Smart and Autonomous Medical Systems (SaAMS) running on Open Health Platforms (OHPs). The collaborative effort will investigate current and future interoperable medical systems including the design and proof-ofconcept demonstrations in the MGH MD PnP lab and other suitable testbeds to identify clinical usage and safety scenarios, sources of interactions between devices, malfunctions and adverse events, remote control and autonomous system considerations, and test methods and standards (either existing or in need of development) across all lifecycle phases. The Parties envision that the results from the collaboration will be useful to the medical device and healthcare provider communities. Results from the collaboration will be made publicly available.

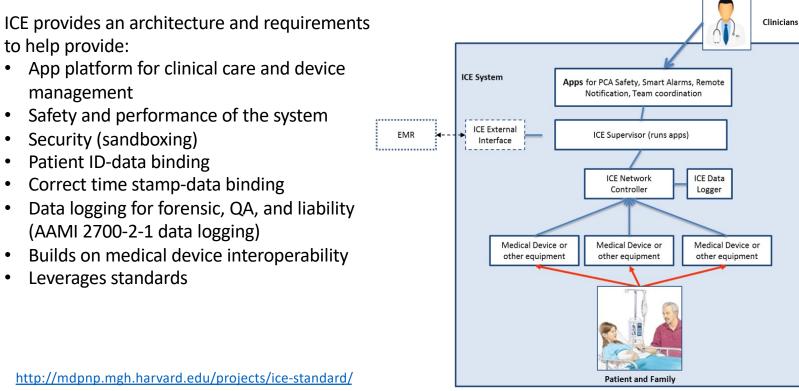
# ICE Standard – "Integrated Clinical Environment"

INTERNATIONAL	(2009 original version of ICE) F2761-09 Medical Devices and Medical Systems — Essential safety requirements for equipment comprising the patient-centric integrated clinical environment (ICE) — Part 1: General requirements and conceptual model	American National Standard	(2019 version of ICE) ANSI/AAMI 2700-1:2019 Medical Devices and Medical Systems—Essential safety and performance requirements for equipment comprising the patient-centric integrated clinical environment (ICE)—Part 1: General
		Copyright to AMA. Reproduced by AMA and permanent of and an element	requirements and conceptual model

Recognized by the FDA 08/2013

## Integrated Clinical Environment Architecture (ICE)

"Essential safety requirements for equipment comprising the patient-centric Integrated Clinical Environment"



Standard recognized by FDA in August 2013 6

http://mdpnp.mgh.harvard.edu/projects/ice-standard/

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# OpenICE – Open-Source Interoperability Research Platform

- An open-source reference implementation of the Integrated Clinical Environment developed under NIH U01 in 2012
- Provides a development and environments and suite of test tools
  - Built-in simulated medical devices
  - Built-in apps and tools
  - Serial and network connected devices
  - Date visibility and export



**OpenICE** Architecture

# Open Medical Device and Data Integration Platforms to support the management of Ebola Virus Disease

# Oct 17, 2014 - Nov 6, 2014

- Friday Oct 17th the White House OSTP Requested an Ebola Care Medical-Technology Response
- First call -> FDA, then to medical device manufacturers and academic collaborators
- Over a 20 day period 19 organizations collaborated to develop and prototype innovative solutions at the MGH MD PnP Lab
- More project details and videos available at

https://mdpnp.mgh.harvard.edu/astra-portfolio/ebola-response/



# Remote Control prototyped for Ebola Response (2014)



### Potential benefits of remote control:

- More rapid response to urgent patient needs (e.g. increase FiO<sub>2</sub>from outside room)
- Reduce room entries
- Reduce PPE consumption
- Assess patients more quickly
- Project supported under NIH/NIBIB U01 grant, and NSF Smart America Closed-Loop Healthcare<sup>2</sup>

<u>1. https://www.wcvb.com/article/local-researchers-testing-remote-control-ebola-care/8211393#</u> in MGH MD PnP lab. See video. 2. https://www.nsf.gov/discoveries/disc\_summ.jsp?cntn\_id=132204 Medical Device Plug-and-Play Interoperability & Cybersecurity (MD PnP) Lab



### Letter of support from Jeffrey Shuren, MD, JD, Director, FDA CDRH

Participation of the US FDA was a powerful incentive for medical device manufacturers to explore innovative medical technology solutions, especially those benefiting from interoperability and collaboration between manufacturers.



#### **DEPARTMENT OF HEALTH & HUMAN SERVICES**

Food and Drug Administration 10903 New Hampshire Avenue Room 5447, Building 66 Silver Spring, MD 20993-0002

November 3, 2014

Julian M. Goldman, MD Director, Medical Device Interoperability Program 65 Landsdowne Street Cambridge, MA, 02139 Dear Dr. Goldman,

Thank you for reaching out to the Center for Devices and Radiological Health (CDRH) via our Emergency Preparedness/Operations and Medical Countermeasures (EMCM) Program.

We understand that The Medical Device "Plug-and-Play" (MD PnP) Interoperability Program, under your coordination, has been asked by the White House Office of Science and Technology Program to mobilize resources among medical device manufacturers and the clinical community, so as to design and demonstrate proof of concept for an interoperable platform that would enable critical care of Ebola-infected patients in an isolation environment with reduced exposure to health care workers.

FDA recognizes the importance of implementing strategies that minimize direct exposure of clinical personnel to patients infected with Ebola virus. We understand that MDPNP, along with its collaborators, are developing potential approaches that would include comprehensive data access and potential remote control of medical devices in the isolation environment, thereby reducing the risk of healthcare worker exposure to the virus.

CDRH recognizes the importance of these efforts and is ready and willing to collaborate with you, the clinical community and your industry partners to demonstrate the potential of this technology in serving this particular public health emergency. We are eager to observe the demonstration taking place Friday November 7th for OSTP, and we look forward to participating in the development of next steps with MDPNP and your medical device partners so as to do our part in enabling advancement of technology that can protect our healthcare workers who put themselves on the front line to promote the public health mission.

Sincerely

Jeffrey Shuren, M.D., J.D. Director Center for Devices and Radiological Health

# COVID-19 IV Pumps and Ventilators placed in hallways!

Typical ICU during COVID-19:

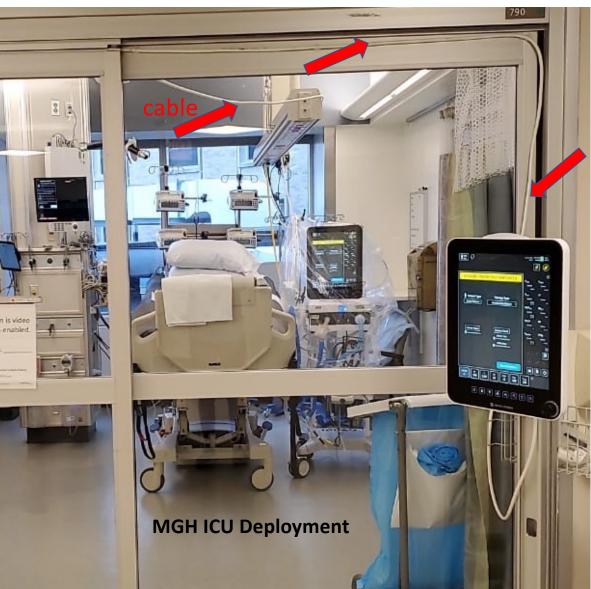
- IV pumps in hallways for access
- Vent control panels in hallways (where possible)
- Cannot hear device alarms outside of room
- Must don PPE to enter room and adjust settings

### 2019 state of the art: Near-patient remote control Nihon Kohden Orange Med NKV-550 Ventilator



Second Active Screen / GUI

- FDA 510K Cleared (prior to pandemic)
- Full ventilator operation (except power on/off)
- Connected through doorway with 10m cable
  - <u>line of site deployment</u>



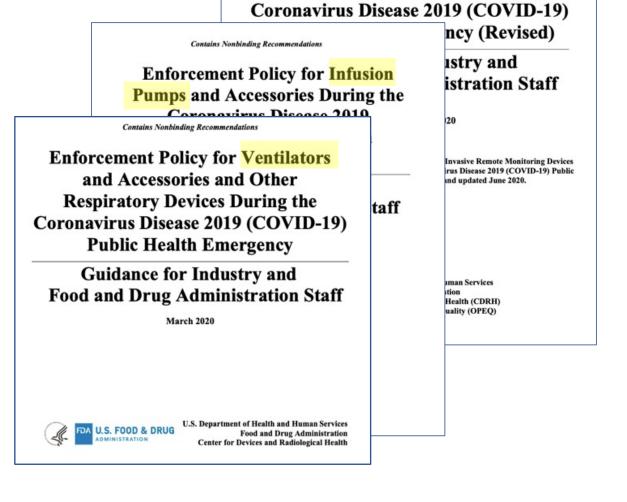
**Contains Nonbinding Recommendations** 

Enforcement Policy for Non-Invasive Remote Monitoring Devices Used to Support Patient Monitoring During the

# FDA Immediate in Effect Guidance 2020

"... Hardware and/or software modifications implementing the capability for remote monitoring and remote adjustment of ventilator parameters" may be added without the need for 510k submission

https://www.fda.gov/media/136318/download Page 8



# Medtronic PB 980 network–enabled remote control provided under FDA COVID-19 FDA enforcement policy



- Medtronic developed a firmware upgrade for the PB980 that allowed remote operation using proprietary software
- Tested in the MGH MD PnP lab in preparation for clinical proof-of-concept deployment in 2020
  - Interoperability
  - Cybersecurity
  - Clinical workflow
  - Installation requirements
  - Assessed role of video to replace line-of-sight connection

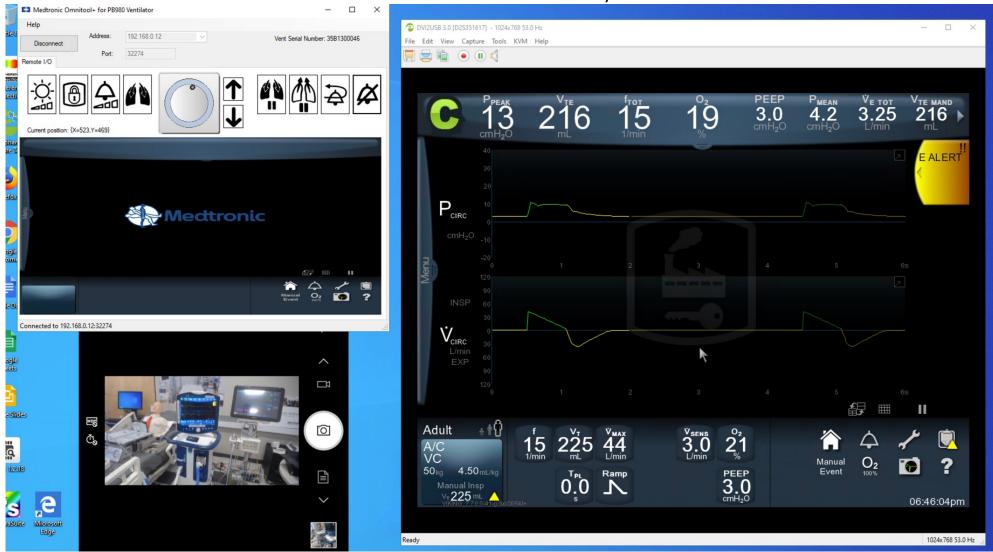
# Medtronic PB 980 Remote-controlled ventilator evaluation - prior to clinical deployment for COVID-19 care



https://vimeo.com/419942297



### Medtronic PB 980 Ventilator controlled over secure connection 8 miles away





Standards Events

Certification M

Membership

# **COVID-19 Resources from the Field**

https://www.aami.org/news-resources/covid-19-resources

Training



As the COVID-19 pandemic continues to impact global health care, AAMI is providing this curated collection of resources to assist the health technology field. While AAMI finds these sources to be credible and has compiled this collection as a service to the field, these references are not endorsed by AAMI and the inclusion of any reference or resource should not be construed as endorsement, promotion, or support of any organization.

To request new or updated information, resources and links, please contact Colleen Elliott at celliot@aami.org.

### Ventilators/Resuscitators/CPAP/BiPAP

These guidance documents have been developed by the AAMI COVID-19 Response Team, made up of manufacturers, clinicians and FDA representatives, to respond to the ventilator shortage emergency.

- AAMI CR501:2020/(R)2022, Emergency Use Ventilator (EUV) Design Guidance (8 April 2020, Revision 1.2)
- AAMI CR502:2020/(R)2022, End User Disclosures for Emergency Use Ventilators (EUVs) (17 April 2020, Revision 1.2)
- AAMI CR503:2020/(R)2022, Emergency Use Resuscitator Systems Design Guidance (8 April 2020, Revision 1)
- AAMI CR504:2020/(R)2022, End User Disclosures for Emergency Use Resuscitator Systems (17 April 2020, Revision 1.1)
- AAMI CR505:2020/(R)2022, Emergency Use CPAP/BiPAP Design Guidance (15 April 2020, Revision 1)
- AAMI CR506:2020/(R)2022, End User Disclosure for CPAP/BiPAP (17 April 2020, Revision 1.1)
- AAMI CR507:2020/(R)2022, Basic Safety of Emergency Use Medical Devices (6 May 2020, Revision 1)
- AAMI CR508:2020/(R)2022, Emergency Use Ventilatory Assistance Helmet (VAH) Design Guidance(16 July 2020, Revision 1)
- AAMI CR509:2020/(R)2022, End User Disclosures for Emergency Use Ventilatory Assistance Helmet (VAH) (16 July 2020, Revision 1)
- AAMI CR511:2020/(R)2022, Emergency use Guidance for Remote Control of Medical Devices(16 December 2020, Revision 1.1)



### **AAMI Consensus Report**

### Emergency Use Guidance for Remote Control of Medical Devices

AAMI CR511:2020/(R)2022



#### Task Group representation

Association for the Advancement of Medical Instrumentation

#### **COVID-19 Response Team Members**

This AAMI Consensus Report (CR) was developed by a task group under the auspices of the AAMI COVID-19 Response Team.

The AAMI COVID-19 Response Team had the following members:

- Cochairs: Jennifer Danieley David Feinstein Julian Goldman Sandy Weininger
- Members: Simona Bancos, FDA/CDRH Andrew Bath, ResMed Inc. Brandon Blakely, FDA/CDRH Brad Bonnette, ECRI Institute Caitlin Brady, Intertek David Busch, UT Southwestern Medical Center Anthony Ciccarello, Philips Steven Dain, University of Western Ontario Rakhi Dalal, FDA/CDRH Jennifer Danieley, FDA/CDRH Andy Doering, Medtronic Simon Dunham, Weill Cornell Medicine Leonard Eisner, Eisner Safety Consultants David Feinstein, American Society of Anesthesiologists (ASA) Anura Fernando, UL LLC Bruce Friedman, GE Healthcare Adrian Gelb, University of California, San Francisco Hamed Ghods, FDA/CDRH Julian Goldman, Mass General Brigham Ralf Heesch, Draeger Medical Systems Inc. Eric Hudson, Medline Fernando Isaza, Philips Michael Jaffe, Cardiorespiratory Consulting LLC Robert Kopotic, Edwards Lifesciences Hubertus Lasthaus, VitalAire Germany Ponleaarun Le, FDA/CDRH Ken LeDez, Memorial University of Newfoundland Ed Madsen, Avanos Medical Phoebe Mainland, Alfred Health Jeff Mandel, Society for Technology in Anesthesia Benoit Marchal, Air Liquide Thomas Marmet, GE Healthcare Debra Milamed, Harvard University Cyndy Miller, Medtronic Inc Campus Bryant Moeller, ResMed Inc. Curtis Morgan, 3M Health Care Akito Ohmura, Teikyo University-Mizonokuchi Hospital David Osborn, Philips

#### 7 Safety requirements and risk control measures 174

Risk management shall be performed to ensure that risk has been reduced to an acceptable level, or failing that, determining that the benefits of using the remote control system outweigh the risk that remains after reducing the risk as low as reasonably practicable.

Safety!

#### 178 7.1 **Disclosure of communication architecture**

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177

The architecture of communication shall be disclosed with sufficient detail in the Instructions for Use to 179 allow the healthcare delivery organization to verify implementation and acceptably manage risk. 180

181 Disclosed information shall include whether the remote control system annunciates audible alarm signals.

182 Note 1 Implementation details may be dependent on both the device manufacturer and the health delivery organization's 183 infrastructure. Sufficient detail in this context includes the aspects of the safety requirements in this section.

184 Note 2 Remote control systems may be constructed from constituents from different manufacturers - those manufacturers may 185 address use hazards somewhat differently, e.g., they may provide (1) different ways of informing the operator about the current state 186 and (2) different controls for operating their respective devices.

187 Note 3 The signal pathways in the remote-control system that are relevant to this guidance document are the four paths listed 188 below. The details of the IT network other than those relating to cybersecurity will not be addressed.

189 a) Direct Wire (point to point) - A direct wired connection is a point to point connection with a single cable or multiple cables 190 that transmits bi-directionally the signals required for monitoring and control of the equipment. This type of connection may 191 use pass-through connectors inside and outside the patient room to maintain a negative room pressure.

192 b) Network Connected-Private/Isolated — A network connected (Private/Wired) connection is a connection where the medical 193 electrical equipment inside the room and/or the auxiliary HMI is connected with a cable to a local area network.

194 c) Wireless-Private/Isolated — A wireless local connection is a wireless connection of the equipment inside the room and/or 195 the auxiliary HMI to each other through a network that is isolated from other networks. This connection is typically a Wi-Fi 196 (See IEEE 802.11x) connection.

197 Wireless/Wired-Shared network connection

198 Note 4 Example of factors affecting risks for different signal pathways listed above include: EMC, QoS, Cybersecurity, Co-199 existence, Connector and cabling reliability, Primary/Auxiliary identification.

200 Note 5 Protocols that allow components to transmit information between them can be used to support levels of interoperability (e.g., syntactic, semantic, conceptual). (See ISO/IEEE 11703-10201) 201

202 7.1.1 Degradation or loss of information

203 Means shall be provided to prevent unacceptable risk arising from degraded or loss of information that is exchanged between the remote control system and the primary medical device. 204

205 Connection/disconnection of the remote control system shall not interfere with the intended use of the 206 primary medical device.

207 Note 1 Causes of degradation can include physical interference with the signal (e.g., electromagnetic in origin (EMC), physical 208 integrity (cable issues)

209 Note 2 Causes of QoS degradation can include bandwidth, latency, jitter, packet drop.

210 Note 3 The loss of function of the remote control system whether through loss of mains power or failure of the power supply, or 211 other cause, will disable the auxiliary HMI and potentially lose the display of information, device control, and alarm display and

212 annunciation. Similarly, loss of auditory or visual alarms may reduce the ability of the clinicians to respond in a timely manner 213 7.1.2 **Conflicting commands** 

214 There shall be a means for ME EQUIPMENT to prevent or resolve conflicting control arising from user action 215 on the remote control system.

216 Authorization of the remote control system communications 7.1.3

When the remote control system communicates with the primary medical device for the first time, there 217 218 shall be a means to confirm that the auxiliary HMI has the authority to remotely control the primary medical 219 device.

- 7.2 Component issues and physical hazards 220
- 221 7.2.1 **Basic safety**

222 Means shall be provided to assure basic safety of the remote control system.

223 Medical Electrical (ME) Equipment shall comply with relevant standards.

224 Remote control system is considered part of the ME system. The basic safety and essential performance aspects of 60601-225 1 apply. The protection against direct physical hazards under normal and single fault conditions is implied and includes tripping on the 226 components of the system such as the cables and a cart if used.

- 227 Manufacturer shall disclose the residual risk.
- 228 7.2.2 Power

Disclosed information shall include whether the remote control system will operate while the medical device 229 230 is not connected to mains power.

Means may be provided for backup power to the auxiliary HMI. 231

232 In the event of loss of mains power, the behavior of the auxiliary HMI shall be disclosed. However, loss of 233 power to the remote control system shall not inadvertently affect the operation of the medical device with 234 its primary HMI.

- 235 NOTE Without backup power, a loss of power will shut down the remote control system and may create a hazardous situation.
- 7.2.3 236 EMC
- 237 IEC 60601-1-2 is recommended but not required.

238 Rationale: The tests of IEC 60601-1-2 are time consuming and expensive and need very specialized

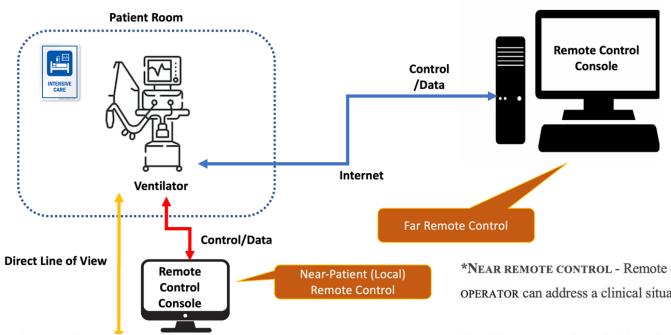
equipment. Requiring these tests would delay availability such that new designs might not be available 239

- 240 when needed. Disclosure that these tests have not been performed and that other equipment must be kept 241
- at a distance should be considered sufficient.

242 Note 1 The hardware used for the remote control system may be vulnerable to radio frequency and electro-magnetic pulses, static 243 discharge, brownouts and voltage spikes. The impact can range from temporary disruption of command and control to permanent 244 damage to circuit boards. Proper shielding, grounding, power conditioning, and/or surge suppression is recommended.

- 245 7.3 Locus of control, information focus
- 246 7.3.1 Locus of control
- 247 Means shall be provided to manage contention for control from multiple sources.

# Near-Patient (Local) Remote Control vs. Far Remote Control



\*NEAR REMOTE CONTROL - Remote control of ME EQUIPMENT from a location where the OPERATOR can address a clinical situation in a timely manner.

Note: Time to respond may be dependent on environment attributes such as physical proximity to the patient environment (ability to make adjustments to the patient/ ME EQUIPMENT UNDER CONTROL), time to take mitigation actions (e.g., time to don/doff), and the line of sight to patient environment.

Definitions in process in AAMI standards committee (IOWG)

\***FAR REMOTE CONTROL** -. Remote control of ME EQUIPMENT from a location where the OPERATOR cannot address a clinical situation in a timely manner.

### Remote Control of Medical Devices

### Table of contents of draft standard

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60	4.2 *RISK MANAGEMENT process
61	4.3 Construction Requirements, Component Issues and Physical Hazards
62	4.3.1 *Data logging
63	4.3.2 *Backup Power
64	4.3.3 *EMC
65	4.3.4 Accompanying Documents
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80	B.2.4 Remote monitoring and control of home care therapeutic devices
81	B.2.5 Remote Control and Monitoring in Transport and Austere Environments
82	B.2.6 Monitoring and Control of an ICU patient at a Central Station and Remotely

### AAMI Remote-Control Standard under development

American National Standard 5/4/2023

### Remote control of medical devices: Lung Ventilators and Intravenous (IV) Infusion Pumps

- Approved xx xxxxxx 20xx by
- AAMI

1

2 3

4

5

6 Approved xx xxxxx 20xx by 7 American National Standards Institute, Inc.

83	B.3 Use Cases
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88 89 90	B.3.2 Use Case 2 – REMOTE CONTROL of monitoring and therapeutic devices from an ICU Central Station of multiple patients in the same care unit with delayed visual contact – 'Proximate' REMOTE CONTROL
91 92	B.3.3 Use Case 3 – REMOTE CONTROL of monitoring and therapeutic devices of a patient in an Air Ambulance in a different continent with no visual contact - 'Far' REMOTE CONTROL
93	Annex C
94	Marking on the outside of REMOTE CONTROL SYSTEMS
95	Bibliography

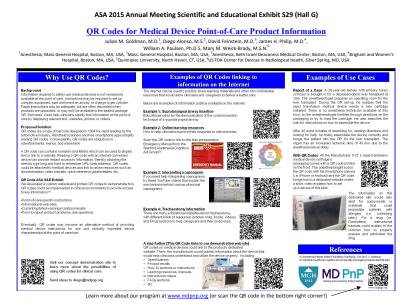
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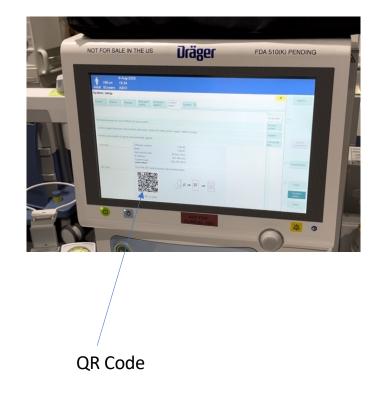
52

Contents

QR Code on screens and devices could help assure availability of point-of-care documentation in emergency conditions:

- APSF 2013 Workshop QR Code public proposal
- ASA 2015 Annual Meeting Scientific Exhibit S29 "QR Codes for Medical Device Point-of-Care Product Information"
  - 3<sup>rd</sup> place award
  - Could link to detailed video instructions
- 2023 DRAGER Atlan example  $\rightarrow$





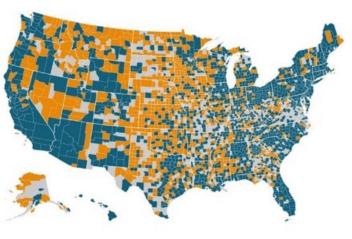


### Disasters stress healthcare system infrastructure, resources, and staff

### Problem:

Locations without ICU beds do not have clinicians who know how to use ventilators – even if they become available. Necessary is a simple, consistent means to reliably and effectively support people who deliver critical care.

Barbashlan et al. NEJM Catalyst (2020) Hospitals with ICU beds Hospitals without ICU beds No Hospitals



Map by tylds zuwikalser Health News analysis of hospital cost reports filed to the Centers for Medicare & Medical Services Source: Kaiser Health News analysis of hospital cost reports filed to the Centers for Medicare & Medical Services tos://khn.org/news/as-coronavirus-spreads-widely-millions-of-older-americans-live-in-countles-with-no-icu-beds/

### Solution:

NETCCN solves this problem by linking remote critical care expertise to frontline clinicians using secure, HIPAA compliant applications on mobile devices.

3 NETCCN teams have deployed in the Public Health Emergency (PHE) to 34 hospitals in 14 states or territories and provided care for almost 5000 patient days.

TiDE – "Technologies in Disaster Environments - enhances NETCCN capabilities.









COL Jeremy C. Pamplin, Commander, jeremy.c.pamplin.mil@mail.mil,

### First Demonstration Presented on December 17, 2021



- Live simulations of clinical scenarios in which remote control of medical devices and interoperable data could improve patient care
- Connected sites in first technical demonstration:
  - Madigan Army Medical Center, JBLM, WA
  - Massachusetts General Hospital, MD PnP Lab, Cambridge, MA
  - Nihon Kohden OrangeMed, Santa Ana, CA
  - Thornhill Medical, Toronto, Canada



- 1. Far remote control from MGH MD PnP Field Hospital\* (Cambridge) to Nihon-Kohden Community Hospital (California) <u>https://vimeo.com/665473382</u>
- 2. Far remote control by MD @Madigan AMC during patient evacuation via ambulance (Toronto, Canada) <u>https://vimeo.com/665476662</u>
- 3. Remote control of ventilator and IV pump (Cambridge) to optimize care https://vimeo.com/665484469
- 4. Remote control from MD PnP Field Hospital observation area (Cambridge) https://vimeo.com/665487966
- 5. Situational awareness dashboard (from all sites to Waltham, MA) https://vimeo.com/665490502
- 6. Teleguidance (from Fort Mill, SC) of point-of care-ultrasound to MD PnP lab https://vimeo.com/665494677

\*Note: These are fictitious hospital names and simulated patients. Geographic locations are accurate. Some remote-control capabilities demonstrated today are under development and not yet intended for clinical use.



### 2<sup>nd</sup> live demonstration

1. Far remote-control of multiple medical devices for mass casualty event, Medical Field Hospital Role II @ Ft. Detrick from Seattle, WA

https://youtu.be/bgaS9nSLwAg?t=1919

2. Far remote management of casualties during enroute care/med-evacuation by UAV from Seattle, WA

https://youtu.be/bgaS9nSLwAg?t=2301

3. Data continuity and automated documentation from multiple vendor devices across continuum of care (Role II -> Medevac -> Hospital)

https://youtu.be/bgaS9nSLwAg?t=2635

4. Integrated single UI data integration and control of multiple vendor IV pumps, ventilator, and patient monitor, simulated ICU, Boston

https://youtu.be/bgaS9nSLwAg?t=2817

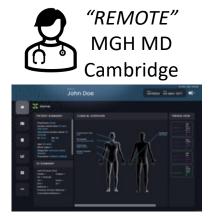
- 5. Remote control safety and performance pre-deployment assessment
  - A. Competition for device control: Risk Management presentation: <u>https://youtu.be/bgaS9nSLwAg?t=3450</u>, and live IV pump control demonstration <u>https://youtu.be/bgaS9nSLwAg?t=4004</u>
  - B. Network performance <a href="https://youtu.be/bgaS9nSLwAg?t=4298">https://youtu.be/bgaS9nSLwAg?t=4298</a>
  - C. Cybersecurity <a href="https://youtu.be/bgaS9nSLwAg?t=4650">https://youtu.be/bgaS9nSLwAg?t=4650</a>

\* Each description is followed by a YouTube video link directly to that section of the video <u>https://www.youtube.com/watch?v=bgaS9nSLwAg</u>. This section starts at 25:35



# Far Remote Control Remote control of NKV-550 Ventilator California ← Cambridge

	Monitoring Data	
1		
•	Control	



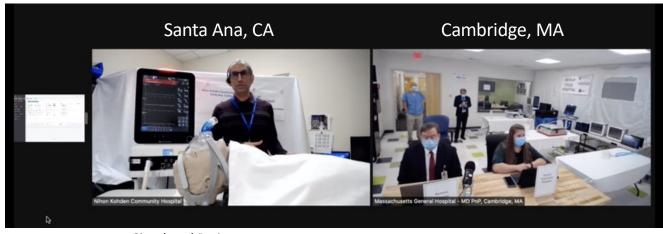
Demonstration #1

NKV-550 Remote Application running on DocBox ICE Apiary Platform

"LOCAL" N-K Community Hospital Santa Ana, CA

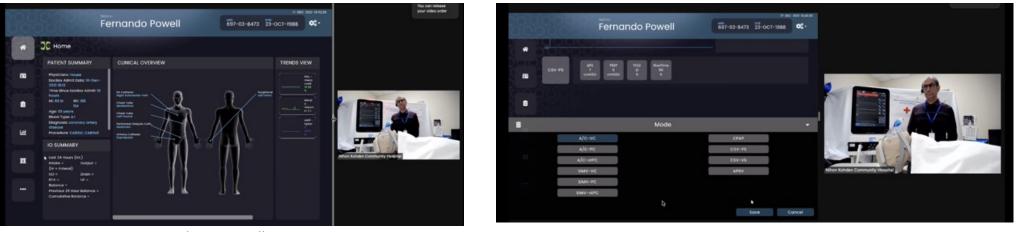
### Scenario:

N-K Hospital: Patient is recovering. Placed on spontaneous ventilatory mode (PS).
Event: Patient is administered pain medication (morphine), stops breathing (apnea), O<sub>2</sub> Sat Drops (82%)
N-K Hospital RN: Detects oxygen saturation is dropping and vent alarm. Calls for help
Remote MD: "I can see the problem and will adjust ventilator for you"
Remote MD: Changes ventilator mode to Volume Control mode.



Simulated Patient

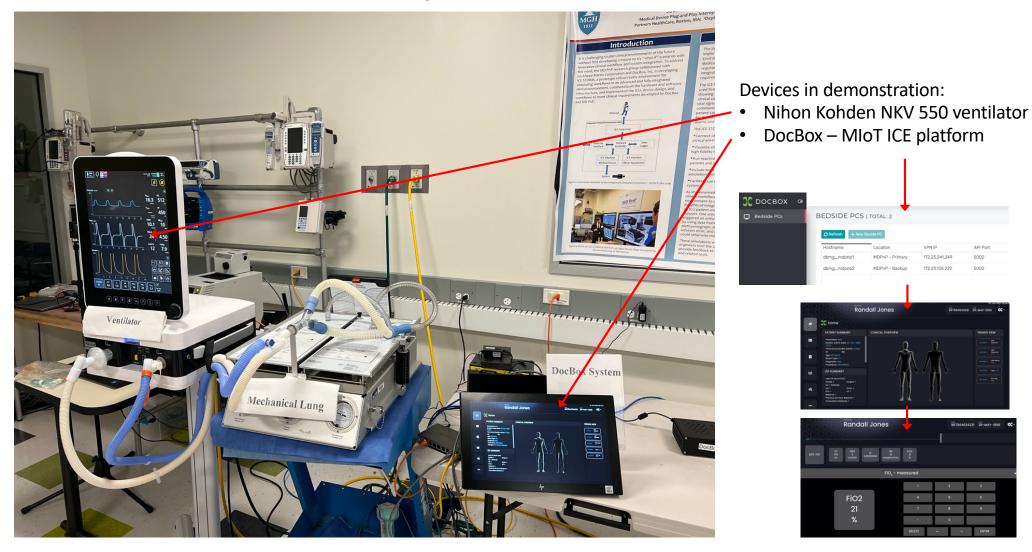
Remote clinicians



Remote ventilator controller

Screenshots from demonstration video 12/17/21

### Demonstration #1

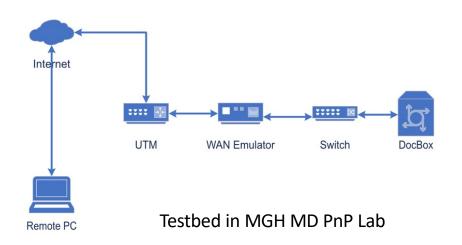


### Remote Control Ventilator Demonstration Using Commercial Medical IoT / ICE Platform

## Remote control safety and performance pre-deployment assessment: Network performance implications

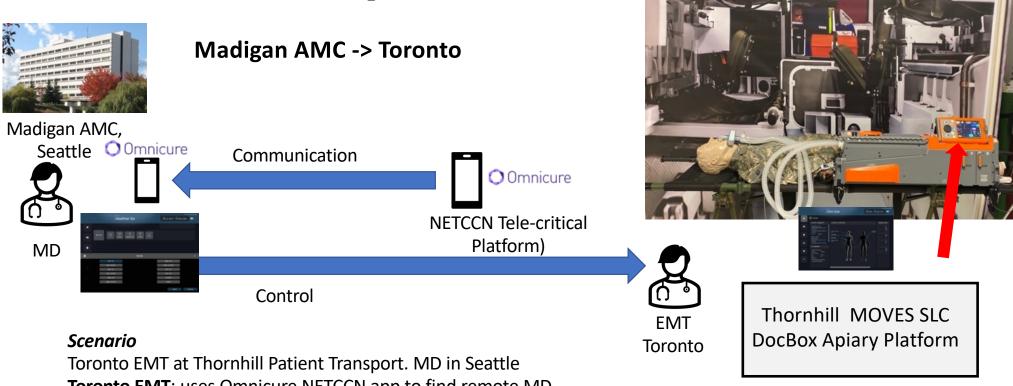
Remote control of Nihon Kohden NKV-550 Ventilator via DocBox ICE platform with insertion of controlled network traffic delay

- Bedside control
- Far-remote control





Far Remote Control During Evacuation of Patient Remote control of Thornhill MOVES SLC (ventilator, monitor, O<sub>2</sub> concentrator)



Demonstration #2

Toronto

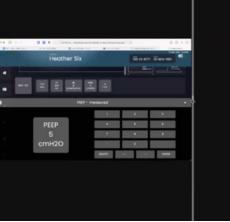
**Toronto EMT**: uses Omnicure NETCCN app to find remote MD **Toronto EMT**: "Ready to transport. Pt is on vent. O<sub>2</sub> sat is low. Help" **Remote MD**: Increase Ventilator O<sub>2</sub> concentration to MAX. Not effective

**Remote MD**: Increases Ventilator PEEP setting. Sat increases.

Demonstration #2



Thornhill ventilator and monitor

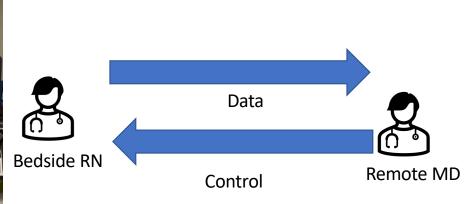


Screenshots from demonstration video 12/17/21

### **Remote Control of an IV Infusion Pump and Ventilator**



### MD PnP ICU, Cambridge, MA





Demonstration #3

Infusion Pump Remote Control and Data OpenICE Research Platform



Sapphire Infusion Pump



Medtronic PB980 Ventilator

### Scenario

**Bedside RN**: O<sub>2</sub> saturation is low. Calls for help. **Remote MD**: Increases PEEP, but BP falls **Remote MD**: Increase norepinephrine infusion rate



Philips MX800 Bedside Patient Monitor

(Also controlled NeuroWave Accupump)



PB 980 Remote control software Medtronic

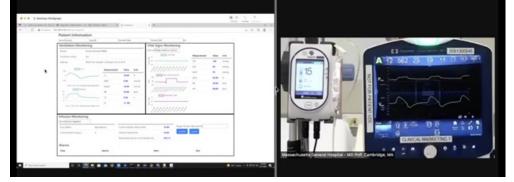
Note – "The Medtronic concept devices used in this demonstration are for nonclinical purposes by Massachusetts General Hospital Medical Device Interoperability Lab."

### **Demonstration #3**

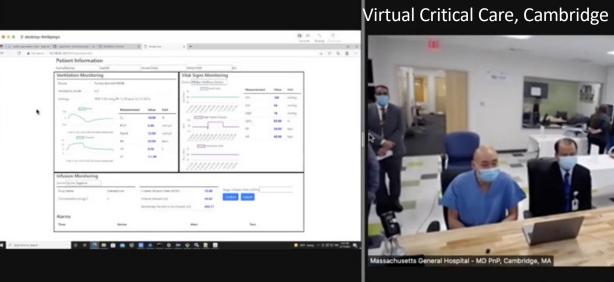


Simulated Patient in Cambridge, MA

Screenshots from demonstration video 12/17/21



Remote ventilator and IV pump control



# Remote-control to manage, support, and evacuate mass casualties @ Ft. Detrick

- A. Far remote-control of multiple medical devices for mass casualty event, Medical Field Hospital @ Ft. Detrick, from Tacoma, WA
- B. Far remote management of casualties during enroute care/med-evacuation by UAV from Seattle, WA

## Point of Injury



#### Medics Arrive and Perform TCCC



#### Move Casualty from POI to Field Hospital







M4 UAV Medical Evacuation Pod Ft. Detrick, MD

UNCLASSIFIED

1: Far remote-control of multiple medical devices for mass casualty event, Medical Field Hospital Role II @ Ft. Detrick from Seattle, WA

Far Remote Control and Monitoring (NKV-550 Ventilator and Philips vital signs monitor)

Casualty @ TATRC (Ft Detrick, MD)  $\leftarrow$  MD in Tacoma, WA



Monitoring Data MD Communication with Medic MD Control of ventilator



Monitoring through DocBox Apiary System and Communication with NETCCN Platform

Scenario:

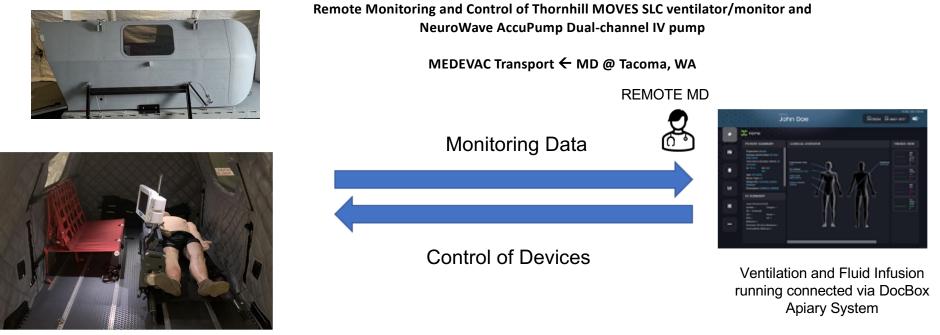
- 4 Patients brought into field hospital with 1 Medic. Two casualties (C1 and C2) are critical. Casualty 1 needs evac.
- Casualties placed on NKV-550 ventilators and AccuPump IV pump.
- Medic: Calls for help with casualties.
- Remote MD monitors patients, assists with adjusting ventilator to resolve clinical issue.
- Medic prepares Casualty 1 for transport

1: Far remote-control of multiple medical devices for mass casualty event, Medical Field Hospital Role II @ Ft. Detrick from Tacoma, WA

Casualty #1 in Medical Field Hospital Role



# 2: Far remote management of casualties during enroute care/med-evacuation by UAV from Tacoma, WA



Scenario:

Casualty on MOVES SLC Ventilator and NeuroWave AccuPump being evacuated.

Medic required remote medical assistance

Medic reports: Patient is hypotensive, oxygenation is good.

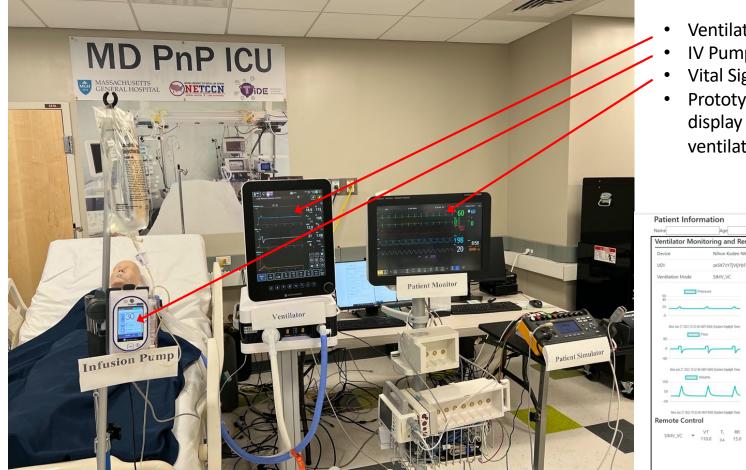
Remote MD sees live data from from the MOVES monitor and ventilator, and IV pump Remote MD decreases sedative rate and reduced ventilator PEEP setting #4 Integrated single UI with data integration and control of multiple vendor IV pumps, ventilator, and patient monitor, simulated ICU, Boston

Remote-control from outside of patient's room:

- Single integrated UI to control multiple brands of IV pumps, ventilator, and view vital signs
- Using OpenICE research ICE platform (Integrated Clinical Environment) in MD PnP Lab @ MGH



#### Tele critical care technology:



- Ventilator
- IV Pump
- Vital Signs Monitor
- Prototype application for Integrated data display and control of pump and ventilator

Patient Information												
lame	Age		Gender					Weight	(lb)			
Ventilator Mon	itoring ar	nd Re	mote	Contr	ol			Vital Signs Monitoring	3			
Device	Nihon K	Nihon Koden NKV550						Device Philips Intellivue Device				
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5			ET CO			0.00	mmHg	60 60		RR	20.00	bpm
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Remote Control								Concentration (mcg/L)			4	
SIMV_VC ¥	VT Ti	RR	PEEP	FiO <sub>2</sub>	PS			Current Infusion Rate (ml/hr)			60.00	
	110.0 0.4	15.0	15.0	21.0	10.0			Volume Infused (ml)				
								Remaining Volume to be Infused	i (ml)			
								remaining volume to be infused	r (mi)			
								Target Infusion Rate (ml/hr) 60				
Opt								Confirm Cancel				

#### Remote Control Verification & Validation at the System Level

Leveraged the MD PnP lab emulation environment to:

- Conduct end-to-end system testing in simulated clinical environments
- Evaluate effectiveness of risk controls using simulated clinical scenarios
- Assess networking requirements for safe remote control using advanced network manipulation technologies

### "Proving" Safety: Safety Assurance Cases

- SAC is a tool to support safety and regulatory submission
- Used in safety critical industries (rail, nuclear)
- FDA drove use for IV infusion pumps to address numerous safety issues
  - Page 9, Infusion Pumps Total Product Life Cycle, <u>https://www.fda.gov/regulatory-information/search-fda-guidance-documents/infusion-pumps-total-product-life-cycle</u>
- Applied to remote control under DoD research portfolio

## What is an Assurance Case?

- An assurance case (AC) is a reasoned, auditable argument created to support the contention that a system of interest will satisfy the [insert specific safety requirement here] (UK Ministry of Defense Standard 00-42)
- An AC is consisted of claim, argument, and evidence nodes, auxiliary supporting information (e.g., context and assumption), and the relation among these nodes. A "safety" AC focuses specifically on **safety**.
- Commercial AC tools are available (e.g., Adelard and GessNet) to support the development, maintenance, review, and auditing of AC, in tabular or graphic formats, or both.

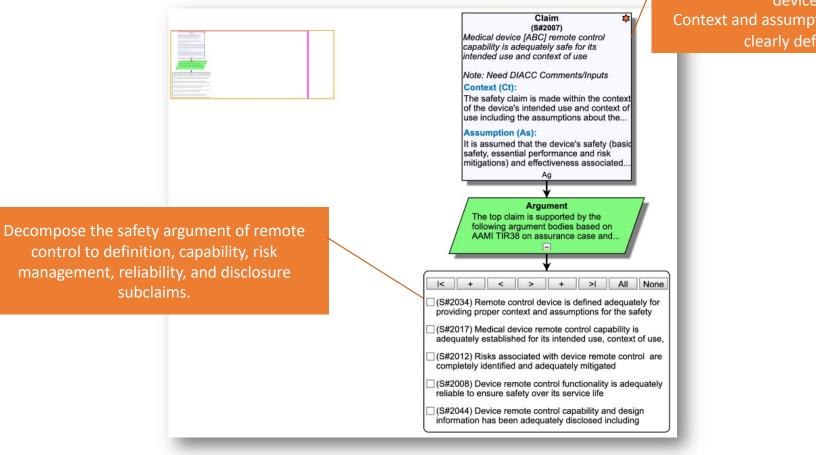
### Generic AC Template for RCMD

- Limited to remote control aspects of device
- Identify key safety aspects of RCMD to demonstrate safety and support integration with remote control applications and systems from other vendors
- Apply industrial standards/best practices, and FDA regulatory framework/requirements wherever applicable
  - AAMI Medical Device Remote Control Draft Standards and AAMI TIR 38
  - FDA Cybersecurity Premarket Guidance
  - ➢ AAMI/UL 2800-1 safety standard for interoperable medical systems
- Developed in Gessnet's TurboAC tool

### AC Template of RCMD

- The generic AC template formulates safety assurance aspects for RCMD as a hierarchy of claims and sub-claims :
  - Clear definition of intended context of use for remote control
  - Implementation of remote-control capabilities
  - Adequate risk management
  - Demonstration of system reliability after the introduction of remote control
  - Sufficient disclosure to other vendors and system integrators

#### Top Level Claim

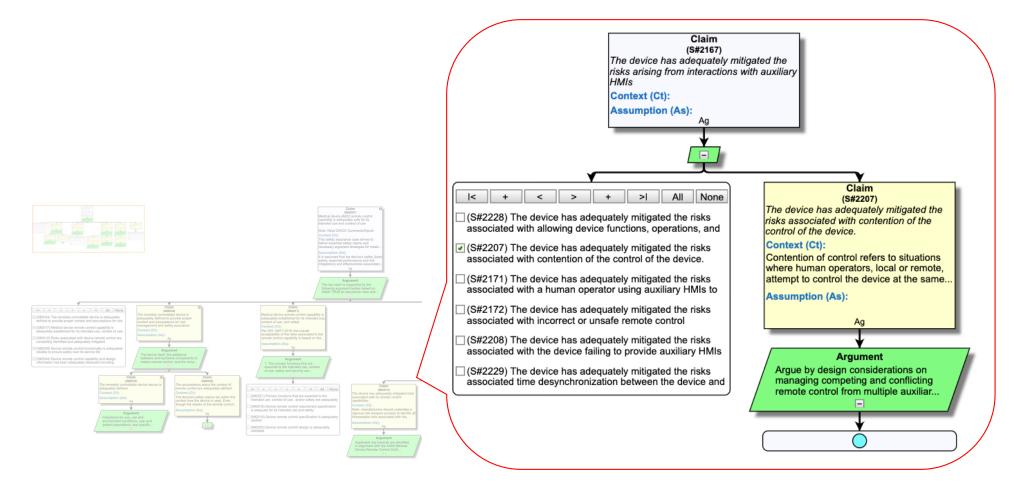


Version 3

Safety Assurance Case for Medical Device Remote Control

Top claim asserts the safety of the remote- control capabilities of the device. Context and assumptions should be clearly defined.

#### Assurance Case Snippet related to Contention/Competing for Control



Top Three Layers of the Generic Assurance Case for Remote Control





The MD PnP Program has an extensive network of senior collaborators and consultants in addition to the core team. **Team**: Clinicians, computer scientists, and biomedical engineers



Julian M. Goldman, MD Program Director



Mosa Al Zowelei, MS Clinical Engineer



David Arney, PhD Lead Engineer



Colin Gorman Program Manager



Yi Zhang, PhD Lead Research Engineer



Bragadeesh Aroulmozhi, MS BME + Developer

More team members: https://mdpnp.mgh.harvard.edu/about/





Thank you!

Julian M. Goldman, MD jmgoldman@mgh.harvard.edu www.jgoldman.info MD PnP Program Manager: Colin Gorman cgorman@mgh.Harvard.edu